



ROHS (E

#### **FEATURES**

- Low Noise Jacketed Cables
- Rugged Integral Strain Relief
- Reliable Silicon MEMS Sensors
- -40 to +105°C Temperature Range
- Compact, Shock Resistant Package
- Low Cross-Axis Sensitivity

#### **APPLICATIONS**

- Auto Safety Crash Testing
- Dummy Instrumentation
- Pedestrian Impact
- Rollover Testing
- Motorsports Applications
- Biomechanics Testing
- Shock & Impact Testing

# **MODEL 633** SIX-DEGREE OF FREEDOM SENSOR

## **SPECIFICATIONS**

- Silicon MEMS Gyro, DC Response
- ±500°/sec to ±24,000°/sec Rate Ranges
- Silicon PR MEMS Accels, DC Response
- ±50g to ±6000g Acceleration Ranges
- SAE J211 & ISO 6487 Compliant
- NHTSA FMVSS 202a Compliant

The Model 633 6-DOF Sensor is an analog sensor that includes outputs of three gyroscope/rate sensors and three DC accelerometers in one small package. The rate sensors and accelerometers are aligned orthogonally to each other which allow the user to measure motions in all 6 degrees of freedom (6-DOF).

Designed specifically for product research and development testing in harsh environments, the Model 633 maintains its precision under high shock conditions. The sensor utilizes silicon MEMS Gyro sensing elements with custom electronics and packaging to produce an angular rate sensor that is highly reliable even under excessive shock and vibration environments. The piezo-resistive MEMS acceleration sensors feature a full bridge output configuration with ideal gas damping tailored for outstanding shock survivability and a flat frequency response to >6kHz

For a similar sensor with lower acceleration and angular rate ranges, TE Connectivity also offers the model 634 6-DOF Sensor.

## PERFORMANCE SPECIFICATIONS

All values are typical at +24°C and 10Vdc excitation unless otherwise stated. TE Connectivity reserves the right to update and change these specifications without notice.

| Parameters                                |              |   |                  |               |                 |           |            |                   |
|---|--------------|---|------------------|---------------|-----------------|-----------|------------|-------------------|
| DYNAMIC (ACCELERATION SEN                 | SORS)        |   |                  |               |                 | - 1 /     |            | Notes             |
| Dash Number                               |              | -050  | -100             | -200          | -500            | -2K       | -6K        | See Ordering Info |
| Range (g)                                 |              | ±50   | ±100             | ±200          | ±500            | ±2000     | ±6000      |                   |
| Sensitivity (mV/g)                        |              | 2.0   | 1.1              | 0.8           | 0.4             | 0.15      | 0.10       | Ratiometric '     |
| Frequency Response (Hz)                   |              | 0-1000  | 0-1200           | 0-1500        | 0-2500          | 0-5000    | 0-6000     | ±1/20B            |
| Natural Frequency (Hz)                    |              | 4000  | 6000             | 8000          | 10000           | 23000     | 26000      | 550               |
| Non-Linearity (%FSO)                      |              | ±1.0  | ±1.0             | ±1.0          | ±1.0            | ±1.0      | ±1.0       | BESL              |
| Transverse Sensitivity (%)                |              | <3  | <3               | <3            | <3              | <3        | <3         | <1% Typical       |
| Shock Limit (g)                           |              | 5000  | 5000             | 5000          | 5000            | 10000     | 10000      |                   |
| Damping Ratio                             |              | 0.5   | 0.5              | 0.5           | 0.3             | 0.15      | 0.05       | Typical           |
|   |              |   |                  |               |                 |           |            |                   |
| Dash Number                               |              | 500   | 11/5             | ek            | 101             | 191       | 2416       | Soo Ordoring Info |
|   |              | -500  | -113             | -01           | -121            | -10K      | -24K       | See Oldening Init |
| Consitivity (m)//dog/200                  |              | ±500  | 1 22             | ±0000         | 12K             |           | 124N       | ±1E0/             |
| Frequency Response (Hz)                   |              | 4.00  | 1.33             | 0.333         | 0.107           | 0.111     | 0.003      | 10%               |
| Neg Linearity (% ESO)                     |              | 0-1000  | 0-1000           | 0-1000        | 0-2000          | 0-2000    | 0-2000     |                   |
| Non-Linearity (%FSO)                      |              | ±0.5  | ±0.5             | ±0.5          | ±0.5            | ±0.5      | ±0.5       | DFOL              |
| Cross-Axis Sensitivity (%)                |              | <1  | <1               | <1            | <1              | <1        | <1         |                   |
| Shock Limit (g)                           |              | 10,000  | 10,000           | 10,000        | 10,000          | 10,000    | 10,000     |                   |
| Residual Noise (mV RMS)                   |              | 3.66  | 1.20             | 3.30          | 1.22            | 1.50      | 1.20       | Passband          |
| ELECTRICAL                                |              |   |                  |               |                 |           |            |                   |
| Zero Acceleration Output (mV). Rat        | te Sensors   | ±100  |                  |               |                 |           |            | Differential      |
| Zero Acceleration Output (mV), Acc        | cel Sensors  | ±25   |                  |               |                 |           |            |                   |
| Excitation Voltage (Vdc), Bate Sen        | sors         | 4.9 to 16   | 0                |               |                 |           |            | Per channel       |
| Excitation Voltage (Vdc), Accel Ser       | isors        | 2 to 10   |                  |               |                 |           |            | Per channel       |
| Excitation Current (mA) Bate Sens         | ors          | <8  |                  |               |                 |           |            | Per channel       |
| Influence of Linear Acceleration (de      | a/sec/a)     | 0 1   |                  |               |                 |           |            | For rate sensors  |
| Common Mode Voltage (Vdc) Bate            | - Sensors    | 2.5   |                  |               |                 |           |            | +5%               |
| Full Scale Output Voltage (Vok), Fide     | ata Sansore  | +2  |                  |               |                 |           |            | 10/0              |
| Output Resistance (0) Rate Sense          | vie Gensols  | <u>100</u>  |                  |               |                 |           |            |                   |
| Input Desistance (02), Nate Sense         | 15           | 400<br>2000 to 5  | -000             |               |                 |           |            |                   |
| Output Resistance (12), Accel Sensor      | S            | 3000 to 5   | 5000             |               |                 |           |            |                   |
| Output Resistance $(\Omega)$ , Accel Sens | UIS          | 3000 10 5   | 0000             |               |                 |           |            | @1001/1           |
|   |              | >100  |                  |               |                 |           |            | @100Vdc           |
| Turn On Time (msec), Rate Sensor          | <100         |   |                  |               |                 |           |            |                   |
| Ground Isolation                          |              | Isolaled  |                  | ig Surface    |                 |           |            |                   |
| ENVIRONMENTAL                             |              |   |                  |               |                 |           |            |                   |
| Thermal Zero Shift, Bate Sensors (        | %ESO)        | +2.5  |                  |               |                 |           |            | -40 to +105°C     |
| Thermal Sensitivity Shift Bate Sen        | sors (%)     | +2.0  |                  |               |                 |           |            | -40 to +105°C     |
| Thermal Zero Shift Accel Sensors          | (mV/°C)      | -0.11 +0  | 11               |               |                 |           |            | -40 to +105°C     |
| Thormal Soncitivity Shift Accol Sor       | (1107, 0)    | 0.25 ±0   | 25               |               |                 |           |            | 40 to +105°C      |
| Operating Temperature (00)                | 15015 (%/ 0) | -0.25 ±0.   | 20               |               |                 |           |            | -40 10 +105 C     |
| Operating Temperature (°C)                |              | -40 to +1   | Colden C         | 2 a al        |                 |           |            |                   |
| Humidity (Active Element & Electro        | nics)        | Hermetic  | ally Solder S    | seal          |                 |           |            |                   |
| Humaity (Housing)                         |              | Eboxà 26  | ealeu, IF05      |               |                 |           |            |                   |
| PHYSICAL                                  |              |   |                  |               |                 |           |            |                   |
| Case Material                             |              | Stainless   | Steel            |               |                 |           |            |                   |
| Cable                                     |              | 2x Cahle  | 2:00.<br>22 #201 | AWG Cond I    | PFA Insulate    | d Braided | Shield PLL | lacket            |
| Weight (cable not included)               |              | 27 JULIES, 127 HOUANG JULIU FEA ILISUIDIEU, DIDIUEU OLIEUU, FU JUCKEL |                  |               |                 |           |            |                   |
| Mounting                                  |              | 2v #2 56  | or M2 Moun       | ting Scrow    |                 |           |            |                   |
| Mounting Torque                           |              | 2X #2.30  | 45 N-m)          | illing Screw  |                 |           |            |                   |
| 1 Output is noticestric to susitation     |              | 4 10-111 (0   | .45 N-III)       |               |                 |           |            |                   |
| Output is ratiometric to excitation       | voltage      |   |                  |               |                 |           |            |                   |
| Calibration Supplied:                     | CS-FREQ-01   | 00 NIS  | T Traceable      | Amplitude C   | alibration to F | R Limit   |            |                   |
|   | US-ARLIN     | NIS   | I I raceable     | Linearity Cal | ibration to FS  | 5 Hange   |            |                   |
| Supplied Accessories:                     | AC-D03548    | 2x #2-56 (3/4" length) Socket Head Cap Screw                          |                  |               |                 |           |            |                   |
| Optional Accessories:                     | 121          | 3-Cł  | nannel Preci     | sion Low Noi  | ise DC Ampli    | fier      |            |                   |

DIMENSIONS



**SCHEMATIC** 



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| 633   | GGG | RRR | ZZZ | XX |  |  |  |
|---|-----|-----|-----|----|--|--|--|
| Range (Accelerometer)   |     |     |     |    |  |  |  |
| 050 = 50g<br>100 = 100g<br>200 = 200g<br>500 = 500g<br>2K = 2000g<br>6K = 6000g   |     |     |     |    |  |  |  |
| Range (Rate Sensor)<br>500 = 500deg/sec<br>1K5 = 1500deg/sec<br>6K = 6000deg/sec<br>12K = 12,000deg/sec<br>18K = 18,000deg/sec<br>24K = 24,000deg/sec |     |     |     |    |  |  |  |
| Cable Length  |     |     |     |    |  |  |  |
| 120 = 120 inches, 10 feet<br>240 = 240 inches, 20 feet<br>360 = 360 inches, 30 feet<br>600 = 600 inches, 50 feet                                      |     |     |     |    |  |  |  |
| 197 = 197 inches, 5 meters<br>276 = 276 inches, 7 meters  |     |     |     |    |  |  |  |
| Reserved for custom designs. Leave blank for standard options listed above.   |     |     |     |    |  |  |  |

#### ORDERING INFORMATION

Example; 633-500-6K-120 Model 633, 500g accel range, 6000deg/sec rate range, 120inch (10ft) cable length

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